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Priorities in Process Algebras

RANCE CLEAVELAND* AND MATTHEW HENNESSY

Computer Science Department, University of Sussex, Falmer, Brighton BN1 9QH, England

An operational semantics for an algebraic theory of concurrency that incorporates a notion of priority into the definition of the execution of actions is developed. An equivalence based on strong observational equivalence is defined and shown to be a congruence, and a complete axiomatization is given for finite terms. Several examples higlight the novelty and usefulness of our approach. © 1990 Academic Press, Inc.

1. INTRODUCTION

Much has been written in recent years about the semantic basis for communicating processes and reactive systems [11, 8, 14]. Intuitively, these are systems which evolve by *interacting*, or *communicating*, with their environment. Systems may perform a variety of actions, some of which may interact with the environment in a particular way; communication is modeled in terms of such interactions.

Most semantic theories for these systems are *operational*. Processes are interpreted using *labeled transition systems*, which are triples of the form $\langle P, \rightarrow, Act \rangle$, where P is the set of processes, Act is the set of actions, and $\rightarrow$ is a relation on $P \times Act \times P$ defining the behaviour of processes. The statement "$p \rightarrow^a q$" means that process p may evolve to process q by performing action a. This form of operational semantics has given rise to a variety of behavioural equivalences on processes [11, 8, 5] and has proven to be a convenient way of defining process behaviour when actions are all of equal importance. However, the approach has a well-recognized flaw when one tries to assign more importance to some actions than to others. Obvious examples of actions which require special treatment include interrupts in hardware systems and time-outs in communications protocols. In addition, certain programming language constructs, such as the "delay" commands in OCCAM [9] and ADA [15] and the disabling construct in LOTOS [4], embody the notion of priority between actions. No satisfactory semantic theory exists for these constructs and for actions with priority in general.

* Current address: Computer Science Department, North Carolina State University, Raleigh, NC 27695-8206.

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In this paper we wish to develop such a theory. To do so we introduce the notion of priority on actions and modify the use of labeled transition systems to develop an operational semantics reflecting these priorities. We then define and axiomatize a new behavioural equivalence analogous to the strong observational equivalence of [11]. We believe that this new semantic theory provides a sound basis for the language constructs and actions mentioned previously.

The paper is organized as follows. In Section 2 we give an example highlighting the problem with existing theories and introduce the idea of prioritized actions. Section 3 defines the language we use and gives our operational semantics. The language is based on CCS, but our method for giving operational semantics can equally well be applied to other languages such as LOTOS [4] and Statecharts [6]. In Section 4 we define a new behavioural equivalence based on strong observational equivalence, and in Section 5 we discuss proof techniques and give a complete axiomatization for finite terms and a proof rule for recursively defined terms. Section 6 presents some examples emphasizing the novelty of our approach, and the final section discusses our conclusions and future plans.

2. Prioritized Actions

The following example in intended to illustrate the inadequacy of existing theories in the presence of interrupts, or, more generally, in the presence of language features which enable and disable actions. Consider the system of Fig. 1. Component C acts as a counter, while INT is designed to halt C when the environment issues a *shut_down* request. In CCS this could be defined by having an internal connection i between INT and C which is used when *shut_down* is performed. In this case the definition of the system would be as follows.

$$SYS \Leftarrow (C_0 \mid INT)\backslash i$$
$$INT \Leftarrow shut\_down \cdot \bar{i} \cdot nil$$
$$C_0 \Leftarrow up \cdot C_1 + i \cdot nil$$
$$C_{n+1} \Leftarrow up \cdot C_{n+2} + down \cdot C_n + \bar{i} \cdot nil.$$

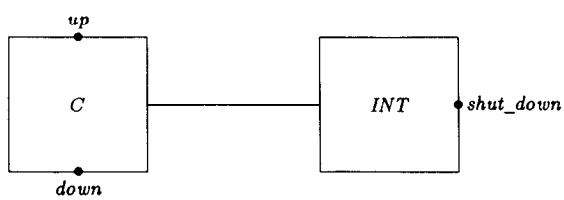


FIG. 1. A two-process system.

However, in the standard operational semantics based on labeled transition systems the following is a valid possible sequence of actions for *SYS*.

up up shut_down up up....

Although the action *shut_down* is performed C_n may choose to ignore indefinitely the offer of communication from *INT* along channel *i*; the operational semantics merely states that actions *up* and *i* are always possible for C_n. Because of this defect in the operational semantics, the resulting behavioural theories [11, 8, 3, 5] give an inadequate account of this system. This semantic shortcoming is not confined to CCS; any language whose operational semantics is given in terms of traditionally defined labeled transition systems will not be able to describe this system correctly.

Intuitively, the desired behaviour of *SYS* can be captured if we associate *priorities* to actions. By assigning a higher priority to *i* than to *up* or *down* we can ensure that when *SYS* reaches the state $(C_n \mid \bar{i} \cdot nil)\backslash i$, the internal synchronization on port *i* must take place next, since it has a higher priority than any of the other possible actions. This is the basis of our approach; we modify the usual operational semantics to take account of priorities and use it to develop what we feel is an adequate semantic theory of such processes.

3. The Language

The syntax of our language is essentially that of pure CCS, although later in the paper we introduce additional operators. For simplicity we assume a two-level hierarchy of priorities; an action is either prioritized or unprioritized. (We should point out that there is no theoretical difficulty is extending our results to sets of actions with a range of discrete priorities.) To model communication we adopt the usual structure of actions used in CCS. Let Λ be a countably infinite set of action labels, and let $A = \Lambda \cup \bar{\Lambda} \cup \{\tau\}$. Additionally, each $a \in A$ has a prioritized version, $\underline{a}$. Let $\underline{A}$ be the set of prioritized actions. Then $Act = A \cup \underline{A}$ is our set of actions.

In the remainder of the paper, let $a, b \in A$, $\underline{a}, \underline{b} \in \underline{A}$, and $\alpha, \beta \in Act$, with $\lambda \in Act - \{\tau, \underline{\tau}\}$. The terms of our language are defined as follows.

$$t ::= nil \mid a \cdot t \mid t|t \mid t + t \mid t\backslash\lambda \mid t[R] \mid x \mid fix(x \cdot t).$$

R, it should be noted, is a *relabeling*, a mapping from Act to Act preserving τ, $\underline{\tau}$, and $\bar{}$ and such that $R(a) \in A$ and $R(\underline{a}) \in \underline{A}$. We also assume that relabelings are finitary in the following sense—if R is a relabeling then the set $\{a \in A \mid a \neq R(a)\}$ is finite. (Note that we do not require that

$$
\begin{array}{lll}
\alpha.s \xrightarrow{\alpha} s & & \\
s \xrightarrow{\alpha} s' & \Rightarrow & s + t \xrightarrow{\alpha} s' \\
t \xrightarrow{\alpha} t' & \Rightarrow & s + t \xrightarrow{\alpha} t' \\
s \xrightarrow{\alpha} s' & \Rightarrow & s|t \xrightarrow{\alpha} s'|t \\
t \xrightarrow{\alpha} t' & \Rightarrow & s|t \xrightarrow{\alpha} s|t' \\
s \xrightarrow{a} s', t \xrightarrow{\bar{a}} t' & \Rightarrow & s|t \xrightarrow{\tau} s'|t' \\
s \xrightarrow{\underline{a}} s', t \xrightarrow{\bar{\underline{a}}} t' & \Rightarrow & s|t \xrightarrow{\tau} s'|t' \\
s \xrightarrow{\alpha} s', \alpha \neq \lambda, \bar{\lambda} & \Rightarrow & s\backslash\lambda \xrightarrow{\alpha} s'\backslash\lambda \\
s \xrightarrow{\alpha} s' & \Rightarrow & s[R] \xrightarrow{R(\alpha)} s'[R] \\
t \xrightarrow{\alpha} t' & \Rightarrow & fix(x.t) \xrightarrow{\alpha} t'[fix(x.t)/x]
\end{array}
$$

FIG. 2. The a priori semantics.

$R(\underline{a}) = \underline{R(a)}$.) We adopt the usual definitions for free and bound variables, open and closed terms, and guarded recursion. In what follows, p, q, and r range over closed terms, which we shall often call *processes*.

The operational semantics of this language is given in two stages. The first stage ignores priorities and is called the a priori operational semantics; the relations $\rightarrow^{\alpha}$ are defined by structural induction on terms in Fig. 2. This definition takes no account of the special properties we wish to assign to prioritized actions. The second stage defines the relations $\rightarrow\!\!\!\triangleright^{\alpha}$, representing the actions which are actually possible. These relations are defined by:

1. if $p \rightarrow^{\underline{a}} q$ then $p \rightarrow\!\!\!\triangleright^{\underline{a}} q$;
2. if $p \rightarrow^{a} q$ and for no $q', \underline{b}$ does $p \rightarrow^{b} q'$ then $p \rightarrow\!\!\!\triangleright^{a} q$.

Intuitively, prioritized actions are unconstrained, while unprioritized actions can happen only if no prioritized actions are possible. Thus $\rightarrow\!\!\!\triangleright$ defines an operational semantics reflecting our intuitions about prioritized actions. Formally, we have defined a labeled transition system $\langle P, \rightarrow\!\!\!\triangleright, Act \rangle$, where P is the set of closed terms.

4. THE BEHAVIOURAL EQUIVALENCE

A variety of behavioural equivalences have been defined on the basis of labeled transition systems. One such equivalence, *strong observational equivalence*, can be described in terms of relations on processes called *bisimulations* [12]. Given the labeled transition system

$$\langle P, \rightarrow, Act \rangle$$

a bisimulation $R \subseteq P \times P$ is a symmetric relation satisfying

$$\langle p, q \rangle \in R \text{ and } p \xrightarrow{\alpha} p' \text{ implies } q \xrightarrow{\alpha} q' \text{ for some } q', \text{ where } \langle p', q' \rangle \in R.$$

Strong observational equivalence, $\sim$, is defined as the largest such bisimulation. It is guaranteed to exist and to be an equivalence relation [12].

This definition can be applied to $\langle P, \Rightarrow, Act \rangle$ to obtain a new equivalence, $\sim_p$. Unfortunately, $\sim_p$ is *not* an adequate behavioural equivalence, because it identifies processes that can intuitively be distinguished. For example,

$$a \cdot p + \underline{b} \cdot q \sim_p \underline{b} \cdot q,$$

since the only transition available to $a \cdot p + \underline{b} \cdot q$ is $a \cdot p + \underline{b} \cdot q \Rightarrow^{b} q$, and yet

$$(a \cdot p + \underline{b} \cdot q)\backslash \underline{b} \not\sim_p (\underline{b} \cdot q)\backslash \underline{b}$$

since $(a \cdot p + \underline{b} \cdot q)\backslash \underline{b}$ may perform an a action while $(\underline{b} \cdot q)\backslash \underline{b}$ may not.

In CCS terms, $\sim_p$ is not a *congruence*, since terms that are $\sim_p$-equivalent may nonetheless give rise to $\sim_p$-inequivalent processes when substituted into a context (a *context* being a term with a "hole"). In the previous example, the context $[\,]\backslash \underline{b}$ distinguishes $a \cdot p + \underline{b} \cdot q$ and $\underline{b} \cdot q$. Relation $\sim_p$ does contain a largest congruence, $\sim_p^C$, where $p \sim_p^C q$ if and only if $C[p] \sim_p C[q]$ for all contexts C. However, there are disadvantages to this type of definition. It does not give rise to the elegant proof techniques normally associated with bisimulation equivalences, and it is dependent on the linguistic constructs allowed in the language, which may not coincide with all programming environments that appear in practice.

Given that we desire an equivalence that is a congruence and that can also be defined in terms of bisimulations, we would like to characterize $\sim_p^C$ as a bisimulation equivalence. We start by defining another operational semantics based on a new arrow, $\rightarrowtriangle$. For convenience, let us say that p is *patient* if $p \rightarrow^{\tau} q$ for no q. Then $\rightarrowtriangle$ is defined by the following two clauses.

1. If $p \rightarrow^{a} q$ then $p \rightarrowtriangle^{a} q$.
2. If $p \rightarrow^{a} q$ and p is patient then $p \rightarrowtriangle^{a} q$.

As before, prioritized actions are not constrained. However, unprioritized actions are preempted by $\underline{\tau}$; they can be performed only by patient processes.

The semantic relation $\rightarrowtriangle$ may also be defined in one stage, without having first to define an a priori semantics. Consider the relation $\rightarrowtail$ given

$$
\begin{array}{lcl}
\alpha.t \overset{\alpha}{\rightarrowtail} t & & \\
s \overset{a}{\rightarrowtail} s' & \Rightarrow & s+t \overset{a}{\rightarrowtail} s' \\
t \overset{a}{\rightarrowtail} t' & \Rightarrow & s+t \overset{a}{\rightarrowtail} t' \\
s \overset{a}{\rightarrowtail} s', t \overset{\underline{\tau}}{\not\rightarrowtail} & \Rightarrow & s+t \overset{a}{\rightarrowtail} s' \\
t \overset{a}{\rightarrowtail} t', t \overset{\underline{\tau}}{\not\rightarrowtail} & \Rightarrow & s+t \overset{a}{\rightarrowtail} t' \\
s \overset{a}{\rightarrowtail} s' & \Rightarrow & s|t \overset{a}{\rightarrowtail} s'|t \\
t \overset{a}{\rightarrowtail} t' & \Rightarrow & s|t \overset{a}{\rightarrowtail} s|t' \\
s \overset{a}{\rightarrowtail} s', t \overset{\bar{a}}{\rightarrowtail} t' & \Rightarrow & s|t \overset{\tau}{\rightarrowtail} s'|t' \\
s \overset{a}{\rightarrowtail} s', s|t \overset{\underline{\tau}}{\not\rightarrowtail} & \Rightarrow & s|t \overset{a}{\rightarrowtail} s'|t \\
t \overset{a}{\rightarrowtail} t', s|t \overset{\underline{\tau}}{\not\rightarrowtail} & \Rightarrow & s|t \overset{a}{\rightarrowtail} s|t' \\
s \overset{a}{\rightarrowtail} s', t \overset{\bar{a}}{\rightarrowtail} t', s|t \overset{\underline{\tau}}{\not\rightarrowtail} & \Rightarrow & s|t \overset{\tau}{\rightarrowtail} s'|t' \\
t \overset{\alpha}{\rightarrowtail} t', \alpha \neq \lambda, \bar{\lambda} & \Rightarrow & t\backslash\lambda \overset{\alpha}{\rightarrowtail} t'\backslash\lambda \\
t \overset{\alpha}{\rightarrowtail} t' & \Rightarrow & t[S] \overset{S(\alpha)}{\rightarrowtail} t'[S] \\
t \overset{\alpha}{\rightarrowtail} t' & \Rightarrow & fix(x.t) \overset{\alpha}{\rightarrowtail} t'[fix(x.t)/x]
\end{array}
$$

$t \overset{\underline{\tau}}{\not\rightarrowtail}$ if and only if $\neg\exists t'.\ t \overset{\underline{\tau}}{\rightarrowtail} t'$.

FIG. 3. A one-stage semantics for CCS with proritized actions.

in Fig. 3; it is defined by induction based on the CCS term structure with the added stipulation that the prioritized transitions of terms are defined before the unprioritized ones. It is worth noting that the relation can be defined by induction solely on the CCS term structure if the hypotheses of the form $s \mid t \not\rightarrowtail^{\underline{\tau}}$ are replaced by the following three hypotheses: $s \not\rightarrowtail^{\underline{\tau}}$, $t \not\rightarrowtail^{\underline{\tau}}$, and $\neg\exists \underline{b}, s', t'.\ s \rightarrowtail^{\underline{b}} s' \wedge t \rightarrowtail^{\bar{b}} t'$. We have chosen the presentation in the figure because it is simpler. Define $t \not\rightarrowtail^{\underline{\tau}}$ to hold exactly when $\neg\exists t'.\ t \rightarrowtail^{\underline{\tau}} t'$. We may now prove the following result.

THEOREM 4.1. *$t \rightarrowtail^{\alpha} t'$ if and only if $t \rightarrowtail^{\alpha} t'$.*

Proof. By induction on the structure of t. Most cases are straightforward; we consider here the case when t is $t_1 \mid t_2$. The induction hypothesis states that, for all actions β, $t_1 \rightarrowtail^{\beta} t_1'$ if and only if $t_1 \rightarrowtail^{\beta} t_1'$ and that $t_2 \rightarrowtail^{\beta} t_2'$ if and only if $t_2 \rightarrowtail^{\beta} t_2'$.

$\Rightarrow$ Assume that $t \rightarrowtail^{\alpha} t'$. If $\alpha \in \underline{A}$ then it follows that either $t_1 \rightarrowtail^{\alpha} t_1'$ and t' is $t_1' \mid t_2$; or $t_2 \rightarrowtail^{\alpha} t_2'$ and t' is $t_1 \mid t_2'$; or $t_1 \rightarrowtail^{\beta} t_1'$, $t_2 \rightarrowtail^{\bar{\beta}} t_2'$, and $\alpha = \underline{\tau}$, for some $\beta \in \underline{A}$. In any of these cases, $t \rightarrowtail^{\alpha} t'$ follows by a straightforward application of the induction hypothesis. Now suppose that $\alpha \in A$. For it to be the case that $t \rightarrowtail^{\alpha} t'$ it must be the case that $t \rightarrow^{\alpha} t'$ and that t is patient. This implies that

1. t_1 is patient, and
2. t_2 is patient, and
3. $\neg\exists \beta \in \underline{A}.\ t_1 \rightarrow^{\beta} t_1' \wedge t_2 \rightarrow^{\bar{\beta}} t_2'$.

From the definition of $\succ\!\!\triangleright$, it follows that $t_1 \succ\!\!\not\triangleright^{\tau}$, $t_2 \succ\!\!\not\triangleright^{\tau}$ and $\neg\exists\beta\in\underline{A}.\ t_1 \succ\!\!\triangleright^{\beta} t_1' \wedge t_2 \succ\!\!\triangleright^{\beta} t_2'$, whence by the induction hypothesis, $t_1 \succ\!\!\not\rightarrow^{\tau}$, $t_2 \succ\!\!\not\rightarrow^{\tau}$, and $\neg\exists\beta\in\underline{A}.\ t_1 \succ\!\!\rightarrow^{\beta} t_1' \wedge t_2 \succ\!\!\rightarrow^{\beta} t_2'$. Therefore $t \succ\!\!\not\rightarrow^{\tau}$. Now consider the ways in which $t \rightarrow^{\alpha} t'$.

1. $t_1 \rightarrow^{\alpha} t_1'$ and t' is $t_1' \mid t_2$. Since t_1 is patient, it follows that $t_1 \succ\!\!\triangleright^{\alpha} t_1'$, and the induction hypothesis then guarantees that $t_1 \succ\!\!\rightarrow^{\alpha} t_1'$. Since it is the case that $t \succ\!\!\not\rightarrow^{\tau}$, we may conclude that $t \succ\!\!\rightarrow^{\alpha} t'$.

2. $t_2 \rightarrow^{\alpha} t_2'$ and t' is $t_1 \mid t_2'$. This case is symmetric to the previous case and is omitted.

3. $t_1 \rightarrow^{\beta} t_1'$ and $t_2 \rightarrow^{\bar{\beta}} t_2'$, for some $\beta\in A$, $\alpha=\tau$, and t' is $t_1' \mid t_2'$. Since t_1 and t_2 are patient it follows that $t_1 \succ\!\!\triangleright^{\beta} t_1'$ and $t_2 \succ\!\!\triangleright^{\bar{\beta}} t_2'$, whence $t_1 \succ\!\!\rightarrow^{\beta} t_1'$ and $t_2 \succ\!\!\rightarrow^{\bar{\beta}} t_2'$ by the induction hypothesis. As $t \succ\!\!\not\rightarrow^{\tau}$ we may conclude that $t \succ\!\!\rightarrow^{\alpha} t'$.

$\Leftarrow$ Assume that $t \succ\!\!\rightarrow^{\alpha} t'$; we must show that $t \succ\!\!\triangleright^{\alpha} t'$. If $\alpha\in\underline{A}$ the result follows from a case analysis on how $t \succ\!\!\rightarrow^{\alpha} t'$ and applications of the induction hypothesis. Now suppose that $\alpha\in A$; it is sufficient to establish that $t \rightarrow^{\alpha} t'$ and that t is patient (or equivalently, $t \succ\!\!\not\triangleright^{\tau}$). From the definition of $\succ\!\!\rightarrow$ it follows that $t \succ\!\!\not\rightarrow^{\tau}$, and this fact implies the following.

1. $t_1 \succ\!\!\not\rightarrow^{\tau}$, and
2. $t_2 \succ\!\!\not\rightarrow^{\tau}$, and
3. $\neg\exists\beta\in\underline{A}.\ t_1 \succ\!\!\rightarrow^{\beta} t_1' \wedge t_2 \succ\!\!\rightarrow^{\bar{\beta}} t_2'$.

Using the induction hypothesis, these imply that $t_1 \succ\!\!\not\triangleright^{\tau}$, $t_2 \succ\!\!\not\triangleright^{\tau}$ and $\neg\exists\beta\in\underline{A}.\ t_1 \succ\!\!\triangleright^{\beta} t_1' \wedge t_2 \succ\!\!\triangleright^{\bar{\beta}} t_2'$, whence it is the case that $t \succ\!\!\not\triangleright^{\tau}$. We now proceed by a case analysis on how $t \succ\!\!\rightarrow^{\alpha} t'$.

1. $t_1 \succ\!\!\rightarrow^{\alpha} t_1'$ and t' is $t_1' \mid t_2$. By the induction hypothesis, $t_1 \succ\!\!\triangleright^{\alpha} t_1'$, and since t is patient it must be the case that $t \succ\!\!\triangleright^{\alpha} t'$.

2. $t_2 \succ\!\!\rightarrow^{\alpha} t_2'$ and t' is $t_1 \mid t_2'$. This case is symmetric to the previous case and is omitted.

3. $t_1 \succ\!\!\rightarrow^{\beta} t_1'$ and $t_2 \succ\!\!\rightarrow^{\bar{\beta}} t_2'$ for some $\beta\in A$, $\alpha=\tau$, and t' is $t_1' \mid t_2'$. From the induction hypothesis it follows that $t_1 \succ\!\!\triangleright^{\beta} t_1'$ and $t_2 \succ\!\!\triangleright^{\bar{\beta}} t_2'$, and since t is patient it follows that $t \succ\!\!\triangleright^{\alpha} t'$. ∎

Since the relations $\succ\!\!\triangleright$ and $\succ\!\!\rightarrow$ are identical, the choice of definition to use is largely one of taste. A one-stage account may be attractive in general, but the appeal of $\succ\!\!\rightarrow$ is reduced somewhat by the presence of negative premises in its definition. We also feel that the two-stage account of $\succ\!\!\triangleright$ explains more clearly the role of priorities in the semantics, and it is therefore the relation we will use in the remainder of the paper.

Let $\simeq$ be the strong equivalence generated by the labeled transition system $\langle P, \rightarrowtriangle, Act \rangle$. Then we have the following.

THEOREM 4.2. *$\simeq$ is a congruence with respect to the operators of CCS.*

Proof. We must show that $\simeq$ is preserved by all the operators in CCS. As the proof is similar for all the operators we examine only $|$. Assume $p \simeq q$; we show that $p|r \simeq q|r$ for arbitrary process r by constructing a bisimulation containing $\langle p|r, q|r \rangle$.

Let $R = \{\langle p'|s, q'|s \rangle | p' \simeq q', s \in P\}$. Clearly, $\langle p|r, q|r \rangle \in R$, and R is symmetric. To show that R is a bisimulation, then, it is sufficient to show that if $\langle p'|s, q'|s \rangle \in R$ and $p'|s \rightarrowtriangle^{\alpha} p''$ then there is a q'' such that $q|s \rightarrowtriangle^{\alpha} q''$ and $\langle p'', q'' \rangle \in R$. If $\alpha \in \underline{A}$ then the argument is straightforward. Suppose, then, that $\alpha \in A$. This means that $p'|s \rightarrow^{\alpha} p''$ and that $p'|s$, and hence $q'|s$, p', q', and s, are patient. There are now three cases to consider. In the first, p'' is $p'''|s$ and $p' \rightarrow^{\alpha} p'''$. Since p' is patient $p' \rightarrowtriangle p'''$, meaning that there is a q''' such that $q' \rightarrowtriangle^{\alpha} q'''$ and $p''' \simeq q'''$. Clearly $q'|s \rightarrowtriangle^{\alpha} q'''|s$, and by construction $\langle p'''|r, q'''|r \rangle \in R$. In the second case p'' is $p'|s'$ and $s \rightarrow^{\alpha} s'$; the argument is similar to that of the previous case and is therefore omitted. In the third case, p'' is $p'''|s'$, $\alpha = \tau$, and there is an $a \in A$ such that $p' \rightarrow^{a} p'''$ and $s \rightarrow^{\bar{a}} s'$. Therefore $p' \rightarrowtriangle^{a} p'''$, and there is a q''' such that $q' \rightarrowtriangle^{a} q'''$ and $p''' \simeq q'''$. Clearly $q'|s \rightarrowtriangle^{\tau} q'''|s'$, and $\langle p'''|s', q'''|s' \rangle \in R$. ∎

It also turns out that $\simeq$ is a congruence with respect to several other language constructs. Of particular interest are the operators corresponding to prioritization of an action (written $p \lceil a$ for $a \neq \tau$) and deprioritization of an action (written $p \lfloor \underline{a}$ for $\underline{a} \neq \underline{\tau}$). Intuitively, $p \lceil a$ prioritizes all a actions p can perform, while $p \lfloor \underline{a}$ deprioritizes all $\underline{a}$ actions p can perform, provided the newly deprioritized action is also available to p. In particular, properties like

$$p \overset{a}{\rightarrowtriangle} q \Rightarrow p \lceil a \overset{a}{\rightarrowtriangle} q \lceil a$$

hold. Defining these operators precisely is somewhat subtle, since their semantics must be defined first in terms of the a priori semantics even though the actions that p may ultimately perform are not defined until the second stage of the semantic specification. The required additions to the a priori semantics are as follows.

1. Prioritization
   (a) If $p \rightarrow^{a} q$ and p is patient then $p \lceil a \rightarrow^{a} q \lceil a$.
   (b) If $p \rightarrow^{a} q$ and p is not patient then $p \lceil a \rightarrow^{a} q \lceil a$.
   (c) If $p \rightarrow^{\alpha} q$ and $\alpha \neq a$ then $p \lceil a \rightarrow^{\alpha} q \lceil a$.

2. Deprioritization

(a) If $p \xrightarrow{a} q$ and p is patient then $p \lfloor \underline{a} \xrightarrow{a} q \lfloor \underline{a}$.

(b) If $p \xrightarrow{a} q$ and p is not patient then $p \lfloor \underline{a} \xrightarrow{a} q \lfloor \underline{a}$.

(c) If $p \xrightarrow{\alpha} q$ and $\alpha \neq \underline{a}$ then $p \lfloor \underline{a} \xrightarrow{\alpha} q \lfloor \underline{a}$.

From these definitions it is easy to see that $\lceil a$ and $\lfloor \underline{a}$ enjoy the following properties with respect to $\rightarrowtriangle$, in addition to the one mentioned above.

- If $p \lceil a \rightarrowtriangle^{a} q \lceil a$ then either $p \rightarrowtriangle^{a} q$ or $p \not\rightarrowtriangle^{a} q$.
- If $p \rightarrowtriangle^{a} q$ and p is patient then $p \lfloor \underline{a} \rightarrowtriangle^{a} q \lfloor \underline{a}$.
- If $p \lfloor \underline{a} \rightarrowtriangle^{a} q \lfloor \underline{a}$ then either $p \rightarrowtriangle^{a} q$ and p is patient or $p \not\rightarrowtriangle^{a} q$.

In particular, it should be noted that if $p \xrightarrow{a} q$, $p \not\xrightarrow{\underline{a}} q$, and $p \not\rightarrowtriangle^{a} q$ (owing to the fact that p is not patient) then $p \lceil a \not\rightarrowtriangle^{a} q \lceil a$. That is, an action is prioritized only if it is "visible" with respect to $\rightarrowtriangle$. Similarly, an action is deprioritized only if it remains visible with respect to $\not\rightarrowtriangle$.

We now have the following result.

THEOREM 4.3. *$\simeq$ is a congruence with respect to prioritization and deprioritization.*

Proof. The proof technique is as in the previous theorem, and as the proofs for prioritization and deprioritization are similar we consider only the latter. Assume $p \simeq q$, and let $R = \{\langle p' \lfloor \underline{a}, q' \lfloor \underline{a} \rangle \mid p' \simeq q'\}$. Clearly $\langle p \lfloor \underline{a}, q \lfloor \underline{a} \rangle \in R$. Since R is symmetric, showing that R is a bisimulation requires us to establish that if $\langle p' \lfloor \underline{a}, q' \lfloor \underline{a} \rangle$ and $p' \lfloor \underline{a} \rightarrowtriangle^{\alpha} p'' \lfloor \underline{a}$ then there is a q'' such that $q' \lfloor \underline{a} \rightarrowtriangle^{\alpha} q'' \lfloor \underline{a}$ and $\langle p'' \lfloor \underline{a}, q'' \lfloor \underline{a} \rangle \in R$. There are two cases to consider.

- $\alpha \in \underline{A}$. Then either $p' \xrightarrow{\alpha} p''$ and $\alpha \neq \underline{a}$ or $p' \xrightarrow{a} p''$, in which case p' is not patient. The first case is trivial; in the second case, since $p' \simeq q'$, q' is not patient, and there is a q'' with $q' \rightarrowtriangle^{a} q''$ and $p'' \simeq q''$. Therefore, $q' \lfloor \underline{a} \rightarrowtriangle^{a} q'' \lfloor \underline{a}$ and $\langle p'' \lfloor \underline{a}, q'' \lfloor \underline{a}, q'' \lfloor \underline{a} \rangle \in R$.

- $\alpha \in A$. So $p' \lfloor \underline{a} \rightarrowtriangle^{\alpha} p'' \lfloor \underline{a}$, and $p' \lfloor \underline{a}$, and hence p' and q', are patient. Now either $p' \xrightarrow{\alpha} p''$ or $p' \xrightarrow{a} p''$. In the former case $p' \rightarrowtriangle^{\alpha} p''$, meaning that there is also a q'' such that $q' \rightarrowtriangle^{\alpha} q''$ and $p'' \simeq q''$. Clearly $q' \lfloor \underline{a} \rightarrowtriangle^{\alpha} q'' \lfloor \underline{a}$ and $\langle p'' \lfloor \underline{a}, q'' \lfloor \underline{a} \rangle \in R$. In the latter case, $p' \rightarrowtriangle^{a} p''$, and thus there is a q'' such that $q' \rightarrowtriangle^{a} q''$ and $p'' \simeq q''$, meaning $\langle p'' \lfloor \underline{a}, q'' \lfloor \underline{a} \rangle \in R$. Moreover, as q' is patient $q' \lfloor \underline{a} \rightarrowtriangle^{\alpha} q'' \lfloor \underline{a}$. ∎

In the augmented language $\sim_p^C$ and $\simeq$ turn out to be the same relation. In one direction the result is straightforward, as the following theorem demonstrates.

THEOREM 4.4. *If* $p \simeq q$ *then* $p \sim_p^C q$.

Proof. Since $\simeq$ is a congruence in the augmented language and $\sim_p^C$ is the largest congruence contained in $\sim_p$, it suffices to establish that if $p \simeq q$ then $p \sim_p q$, which in turn holds if $\simeq$ is a bisimulation with respect to $\rightarrowtriangle$. As $\simeq$ is symmetric, to establish that $\simeq$ is such a bisimulation, assume $p \simeq q$ and $p \rightarrowtriangle^{\alpha} p'$; we must show that there is a q' such that $q \rightarrowtriangle^{\alpha} q'$ and $p' \simeq q'$. Since $p \rightarrowtriangle^{\alpha} p'$ implies that $p \rightarrowtail^{\alpha} p'$ the result follows easily from a case analysis on why $p \rightarrowtriangle^{\alpha} p'$. ∎

Proving the converse of the previous theorem is somewhat more involved. Intuitively, the difference between $\rightarrowtriangle$ and $\rightarrowtail$ arises in their treatments of unprioritized actions in the presence of external (i.e., non-$\underline{\tau}$) prioritized actions. Therefore, if we define a context $D[\,]$ that deprioritizes all external actions in an appropriate way, then $\rightarrowtriangle$ transitions for $D[p]$ correspond to $\rightarrowtail$ transitions for p, and we can relate $\sim_p^C$ and $\simeq$. To this end, let p and q be processes, and let $D_{p,q}[\,]$ be the context defined as follows. First, let $S_{\mathrm{U}}(p)$ and $S_{\mathrm{P}}(p)$ be the "unprioritized" and "prioritized" sorts, respectively, of p. From the definition of the terms in our language and the restrictions we place on relabelings, it follows that these sets are finite. Now define the relabeling $L_{p,q}$ as

$$L_{p,q}(\alpha) = \begin{cases} \alpha & \text{if } \alpha \in \underline{A} \\ \alpha & \text{if } \alpha \in A \text{ and } \underline{\alpha} \notin S_{\mathrm{P}}(p) \cup S_{\mathrm{P}}(q) \\ c_{\alpha} & \text{otherwise,} \end{cases}$$

where $c_{\alpha} \in A$, $c_{\bar{\alpha}} = \overline{c_{\alpha}}$, $c_{\alpha} \neq c_{\beta}$ if $\alpha \neq \beta$, and $\underline{c_{\alpha}} \notin S_{\mathrm{P}}(p) \cup S_{\mathrm{P}}(q) \cup \underline{S_{\mathrm{U}}(p)} \cup \underline{S_{\mathrm{U}}(q)}$. Since the set A of actions is infinite, such a c_{α} is guaranteed to exist. $L_{p,q}$ essentially maps unprioritized actions in p and q whose prioritized versions also exist in p and q to unique unprioritized actions with no prioritized counterparts in the processes. Now define $S_{p,q} = S_{\mathrm{P}}(p) \cup S_{\mathrm{P}}(q)$, and let $D_{p,q}[r] = ([r][L_{p,q}]) \lfloor S_{p,q}$, where $\lfloor S$ is the obvious generalization of the deprioritization operator to sets of actions. This context uniquely deprioritizes actions in p and q.

The definition of $D_{p,q}[\,]$ gives rise to an equivalence between processes in much the same way in which the set of all contexts $C[\,]$ gives rise to the equivalence $\sim_p^C$. Define $p \sim_p^D q$ to hold exactly when $D_{p,q}[p] \sim_p D_{p,q}[q]$. Clearly, if $p \sim_p^C q$ then $p \sim_p^D q$.

Several properties of $D_{p,q}[\,]$ and $\sim_p^C$ deserve comment, since they will be used in the proof of the next theorem. To begin with, if p is patient then for no $\underline{a}$, q, and r does $D_{p,q}[p] \rightarrowtriangle^{a} r$; this results from the fact that because p is patient, the deprioritization operator in $D_{p,q}[\,]$ deprioritizes all prioritized actions that p may initially perform. Also, if $\alpha \in A$ and $D_{p,q}[p] \rightarrowtriangle^{L_{p,q}(\alpha)} D_{p,q}[p']$ then $p \rightarrowtail^{\alpha} p'$, since in this case p must be

patient. Finally, if $S_P(p') \subseteq S_P(p)$, $S_U(p') \subseteq S_U(p)$, $S_P(q') \subseteq S_P(q)$, and $S_U(q') \subseteq S_U(q)$, then $D_{p',q'}[p'] \sim_p D_{p',q'}[q']$ (and thus $p' \sim_p^D q'$) if and only if $D_{p,q}[p'] \sim_p D_{p,q}[q']$. This follows from the fact that both $D_{p,q}$ and $D_{p',q'}$ uniquely deprioritize actions in p' and q'. It should be noted that if $p \rightarrow^{\alpha} p'$ then $S_P(p') \subseteq S_P(p)$ and $S_U(p') \subseteq S_U(p)$.

We are now able to prove the next theorem.

THEOREM 4.5. *If* $p \sim_p^C q$ *then* $p \simeq q$.

Proof. Since $\sim_p^C \subseteq \sim_p^D$ it suffices to show that $\sim_p^D$ is a bisimulation for $\langle P, \rightarrowtriangle, Act \rangle$. Clearly $\sim_p^D$ is symmetric. Assume $p \sim_p^D q$ and $p \rightarrowtriangle^{\alpha} p'$; we must show that there is a q' such that $q \rightarrowtriangle^{\alpha} q'$ and $p' \sim_p^D q'$. There are three cases.

- $\alpha = \underline{a} \in \underline{A}$ and p is patient. Then $D_{p,q}[p]$ is patient, and $D_{p,q}[p] \rightarrow^{a} D_{p,q}[p']$. From the properties above it follows that $D_{p,q}[p] \rightarrowtriangle^{a} D_{p,q}[p']$, and this implies that there is a q' such that $D_{p,q}[q] \rightarrowtriangle^{a} D_{p,q}[q']$ and $D_{p,q}[p'] \sim_p D_{p,q}[q']$. Again from the properties mentioned above, $p' \sim_p^D q'$, and it is easy to establish that $q \rightarrowtriangle^{\underline{a}} q'$.

- $\alpha \in \underline{A}$ and p is impatient. This case is routine because the deprioritization in $D_{p,q}[\,]$ has no effect.

- $\alpha \in A$. Then p, and hence $D_{p,q}[p]$, $D_{p,q}[q]$ and q, must be patient. This implies that $D_{p,q}[p] \rightarrowtriangle^{L_{p,q}(\alpha)} D_{p,q}[p']$, and there is therefore a q' such that $D_{p,q}[q] \rightarrowtriangle^{L_{p,q}(\alpha)} D_{p,q}[q']$ and $D_{p,q}[p'] \sim_p D_{p,q}[q']$, meaning that $p' \sim_p^D q'$. Moreover, as $D_{p,q}[q] \rightarrowtriangle^{L_{p,q}(\alpha)} D_{p,q}[q']$, by the above properties it must be the case that $q \rightarrowtriangle^{\alpha} q'$. ∎

5. PROOF TECHNIQUES

In this section we briefly sketch the proof techniques we have for deriving equivalences. Because $\simeq$ is defined as a bisimulation equivalence a natural and often effective way of proving $p \simeq q$ is to exhibit a bisimulation R (with respect to $\rightarrowtriangle$) which contains the pair $\langle p, q \rangle$. Indeed, the well-known bisimulation construction algorithms for deciding bisimulation equivalence [10, 13] may be adapted to our semantics.

Alternatively, there is a set of equivalence-preserving syntactic transformations based on the well-known ones for strong bisimulation equivalence [7]; these are listed in Fig. 4. The usual laws for $+$, *nil*, $\backslash\lambda$, and $[R]$ remain valid; however, the presence of $\underline{\tau}$ necessitates the new law P. This is readily seen to be satisfied by $\simeq$ because of the preemptive power of $\underline{\tau}$. The interleaving law from [7] also needs a slight modification because of the presence of two kinds of synchronization actions, τ and $\underline{\tau}$; this law appears

A1	$x+x$	$=$	x
A2	$x+y$	$=$	$y+x$
A3	$x+(y+z)$	$=$	$(x+y)+z$
A4	$x+nil$	$=$	x
P	$a.x+\underline{\tau}.y$	$=$	$\underline{\tau}.y$
INT	Let p, q denote $\sum \alpha_i.p_i, \sum \beta_j.q_j$, respectively. Then		
	$p\|q$	$=$	$\sum \alpha_i.(p_i\|q) + \sum \beta_j.(p\|q_j) + \sum_{\alpha_i=\overline{\beta_j}\in A} \tau.(p_i\|q_j) + \sum_{\alpha_i=\overline{\beta_j}\in A} \underline{\tau}.(p_i\|q_j)$
RES1	$nil\backslash\lambda$	$=$	nil
RES2	$(\alpha.x)\backslash\lambda$	$=$	$\begin{cases} nil & \text{if } \alpha \in \{\lambda, \overline{\lambda}\} \\ \alpha.(x\backslash\lambda) & \text{otherwise} \end{cases}$
RES3	$(x+y)\backslash\lambda$	$=$	$(x\backslash\lambda)+(y\backslash\lambda)$
REL1	$nil[R]$	$=$	nil
REL2	$(\alpha.x)[R]$	$=$	$R(\alpha).(x[R])$
REL3	$(x+y)[R]$	$=$	$x[R]+y[R]$

FIG. 4. The equational characterization of $\simeq$ for CCS.

in Fig. 4 as INT. Let E denote the set of equations in Fig. 4, and let $p =_E q$ mean that p can be transformed into q by application of the equations in E. The next theorem says that these equations completely characterize the new equivalence for finite (i.e., "fix-free") terms.

THEOREM 5.1. *For finite CCS terms p, q, $p \simeq q$ if and only if $p =_E q$.*

Proof. In one direction it is sufficient to show that $\simeq$ satisfies all of the equations in E. The only non-trivial case is the interleaving law. Let p, q be as in the law INT, and let r denote the summation mentioned on the right-hand side of the law. To show $p\,|\,q \simeq r$ it is sufficient to show that

$$p\,|\,q \overset{\alpha}{\rightarrowtriangle} s \Leftrightarrow r \overset{\alpha}{\rightarrowtriangle} s.$$

If α is prioritized this is obvious. It is also trivially the case that $p\,|\,q \rightarrow^{\alpha} s \Leftrightarrow r \rightarrow^{\alpha} s$. Therefore, for $\alpha \in A$,

$$p\,|\,q \overset{\alpha}{\rightarrowtriangle} s \Leftrightarrow p\,|\,q \overset{\alpha}{\rightarrow} s \text{ and } p\,|\,q \text{ is patient}$$

$$\Leftrightarrow r \overset{\alpha}{\rightarrow} s \text{ and } r \text{ is patient}$$

$$\Leftrightarrow r \overset{\alpha}{\rightarrowtriangle} s.$$

Thus, if $p =_E q$ then $p \simeq q$.

Conversely, suppose $p \simeq q$. In order to show that $p =_E q$ we use a standard approach taken from Section 4.1 in [7]. We assume some

familiarity on the part of the reader with the techniques used there and hence provide only the essential details of the argument here. Clearly, INT, RES1–3 and REL1–3 may be used to eliminate all occurrences of $|$, $\backslash\lambda$, and $[R]$ from any term. Because of A1–4 we may therefore assume that each term can be reduced to a sum form, $\sum \alpha_i \cdot p_i$. The new law P may now be applied to obtain a term $\sum_{j \in J} \beta_j \cdot p_j$ that satisfies the restriction

$$\text{If } \beta_j = \underline{\tau} \text{ for some } j \in J \text{ then for all } j \in J, \beta_j \in \underline{A}.$$

Let us call these terms *normal forms* if each of the p_j is a normal form. Such a term $n = \sum \beta_j \cdot n_j$ satisfies the property

$$n \overset{\alpha}{\rightarrowtail} n' \Leftrightarrow \text{there is some } j \text{ such that } \alpha \text{ is } \beta_j \text{ and } n' \text{ is } n_j. \tag{1}$$

Applying the above arguments inductively, we may assume that p and q have normal forms n and m, respectively. Therefore, to show that $p =_E q$ it is sufficient to show that $n =_E m$. To show this, it is sufficient to show that for an arbitrary j, $\beta_j \cdot n_j + m =_E m$. Now $n \overset{\beta_j}{\rightarrowtail} n_j$ and so there is an m' such that $m \overset{\beta_j}{\rightarrowtail} m'$ and $n_j \simeq m'$. By (1), $\beta_j \cdot m'$ must be a summand of m, and therefore $m =_E m + \beta_j \cdot m'$. By induction we may assume that $n_j =_E m'$ and hence $m =_E m + \beta_j \cdot n_j$. ∎

We now consider proof rules for recursive terms. The development of the standard results is complicated somewhat by the fact that the basic a priori moves, $\rightarrow^{\alpha}$, are defined by structural induction on (open) terms instead of by the more usual inductive definition. This is necessary because the clauses in the definition of $\rightarrow^{\alpha}$ for the prioritization and deprioritization operators have negative antecedents and therefore cannot be used in an inductive definition specified as the least relation satisfying a collection of clauses. One consequence of this is that we must confine ourselves to guarded recursions, since in the more general case certain desirable properties of recursively defined processes—such as $fix(x \cdot t) \simeq t[fix(x \cdot t)/x]$—do not hold. This restriction, however, is a standard one adopted in the literature and is indeed a reasonable one. The relevant property of guarded expressions, which we leave to the reader to verify, is

$$\text{If } x \text{ is guarded in } t \text{ then } (t[u/x] \overset{\alpha}{\rightarrow} r \Leftrightarrow r \text{ is } t'[u/x] \text{ and } t \overset{\alpha}{\rightarrow} t'). \tag{2}$$

Another useful property, which is trivial to prove, is

$$(p \overset{\alpha}{\rightarrow} r \Leftrightarrow q \overset{\alpha}{\rightarrow} r) \text{ implies } p \simeq q. \tag{3}$$

More generally, let R be any bisimulation in the a priori semantics $\langle P, \rightarrow, Act \rangle$. Then

$$\langle p, q \rangle \in R \text{ implies } p \simeq q. \tag{4}$$

This follows easily from the fact that such a R is also a bisimulation in the operational semantics $\langle P, \succ\!\!\rightarrow, Act \rangle$.

With these results we can derive many of the expected properties of the fixed point operator. The first states that $fix(x \cdot t)$ is indeed a fixed point of the equation $x \simeq t$.

THEOREM 5.2. $fix(x \cdot t) \simeq t[fix(x \cdot t)/x]$.

Proof. From the property (2) and the definition of $\rightarrow$ it follows that $fix(x \cdot t) \rightarrow^{\alpha} r$ if and only if $t[fix(x \cdot t)/x] \rightarrow^{\alpha} r$. The result follows from (3).

It is possible to extend $\simeq$ to open terms in a natural way. Let a *substitution* σ be a mapping from variables to P, and for a term t let $t\sigma$ represent the obvious (closed) term. Then define $t \simeq u$ to hold exactly when for all substitutions σ, $t\sigma \simeq u\sigma$. The next result states that this extended $\simeq$ behaves properly with respet to fix considered as an operator on terms.

THEOREM 5.3. *If* $t \simeq u$ *then* $fix(x \cdot t) \simeq fix(x \cdot u)$.

Proof. The argument follows the lines of the proof of Proposition 4.6(2) in [12], which is the corresponding result for the standard bisimulation equivalence based on $\rightarrow$. We may assume that both $fix(x \cdot t)$ and $fix(x \cdot u)$ are closed. Let $fv(t)$ represent the set of free variables in the term t, and let

$$R = \{ \langle r[fix(x \cdot t)/x], r[fix(x \cdot u)/x] \rangle \mid fv(r) \subseteq \{x\} \}.$$

We show that $R \cup R^{-1}$ is a bisimulation in $\langle P, \succ\!\!\rightarrow, Act \rangle$ up to $\simeq$.

As $R \cup R^{-1}$ is symmetric it is sufficient to show that if $r[fix(x \cdot t)/x] \succ\!\!\rightarrow^{\alpha} p$ then $r[fix(x \cdot u)/x] \succ\!\!\rightarrow^{\alpha} q$ for some q such that there is a q' with $q \simeq q'$ and $\langle p, q' \rangle \in R$. Consider the case when $\alpha \in \underline{A}$; the case where $\alpha \in A$ is similar and is left to the reader. Then $r[fix(x \cdot t)/x] \rightarrow^{\alpha} p$. We prove by induction on the length of the proof of this derivation that $r[fix(x \cdot u)/x] \rightarrow^{\alpha} q$ (and therefore $r[fix(x \cdot u)/x] \succ\!\!\rightarrow^{\alpha} q$) for some q such that there is a q' with $q \simeq q'$ and $\langle p, q \rangle \in R$. We now need a case analysis on the structure of r; we consider here the case where r is x, since the proofs of the other cases do not differ significantly from those found in [12]. In this case we have $fix(x \cdot t) \rightarrow^{\alpha} p$, and therefore p must be of the form $t'[fix(x \cdot t)/x]$, where $t \rightarrow^{\alpha} t'$. As t is guarded, this means that $t[fix(x \cdot t)/x] \rightarrow^{\alpha} t'[fix(x \cdot t)/x]$; moreover, the length of this derivation is exactly the same as that of $t \rightarrow^{\alpha} t'$, which is less than that of $fix(x \cdot t) \rightarrow^{\alpha} p$. So we may apply the induction hypothesis to obtain $t[fix(x \cdot u)/x] \rightarrow^{\alpha} q''$ for some q'' such that there is a q' with $q'' \simeq q'$ and $\langle p, q' \rangle \in R$. But $t \simeq u$, so $t[fix(x \cdot u)/x] \simeq u[fix(x \cdot u)/x]$. So $u[fix(x \cdot u)/x] \rightarrow^{\alpha} q$ for some q such that $q \simeq q'$ and $\langle p, q' \rangle \in R$. Now consider the derivation $u[fix(x \cdot u)/x] \rightarrow^{\alpha} q$. By (2), q must be of the form $u'[fix(x \cdot u)/x]$, where $u \rightarrow^{\alpha} u'$, so $fix(x \cdot u) \rightarrow^{\alpha} q$. ∎

The final result we show is a form of induction that is often called "unique fixed point induction."

THEOREM 5.4. *If* $p \simeq t[p/x]$ *then* $p \simeq fix(x \cdot t)$.

Proof. In light of Theorem 5.2 it suffices to show that if $p \simeq t[p/x]$ and $q \simeq t[q/x]$ then $p \simeq q$. The proof of this follows that of the corresponding result for strong bisimulation, Proposition 4.9 of [12]. Let p, q be such that $p \simeq t[p/x]$ and $q \simeq t[q/x]$. To show that $p \simeq q$ we prove that $R = \{\langle r[p/x], r[q/x]\rangle \mid fv(r) \subseteq \{x\}\}$ is a bisimulation up to $\simeq$. The details of the proof are essentially the same as those in [12] and are omitted. ∎

6. EXAMPLES

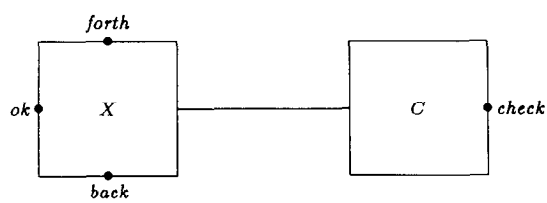
In this section we present two examples that illustrate the usefulness of our approach. The first example defines a system consisting of two processes: a process X that flips back and forth between two states and a process C that checks that the first process is running properly. The implementation of this system in our language appears in Fig. 5.

One desirable property of this system would be that each *check* action is followed by an *ok*, an acknowledgement that X is running. In pure CCS, this is not the case; indeed, the (infinite) sequence of actions

check back forth back forth ...

is possible, owing to the fact that X is not required to synchronize with C after C performs a *check*. In our framework, this cannot happen, since i is prioritized. In fact, it is the case that

$$Sys \simeq Spec,$$



$$X \Leftarrow back.X' + \underline{i}.ok.\bar{\underline{i}}.X$$
$$X' \Leftarrow forth.X + \underline{i}.ok.\bar{\underline{i}}.X'$$
$$C \Leftarrow check.\bar{\underline{i}}.\underline{i}.C$$
$$Sys \Leftarrow (X|C)\backslash \underline{i}$$

FIG. 5. A two-process system.

where *Spec* is defined as

$$Spec \Leftarrow back.Spec' + check.\underline{\tau}.ok.\underline{\tau}.Spec$$

$$Spec' \Leftarrow forth.Spec + check.\underline{\tau}.ok.\underline{\tau}.Spec'.$$

To prove this, let $Sys' = (X' \mid C)\backslash i$. It suffices to show that

$$Sys = Spec$$

$$Sys' = Spec'.$$

Using the unique fixed point rule, it is sufficient to show that

$$Sys = back.Sys' + check.\underline{\tau}.ok.\underline{\tau}.Sys \tag{1}$$

$$Sys' = forth.Sys + check.\underline{\tau}.ok.\underline{\tau}.Sys'. \tag{2}$$

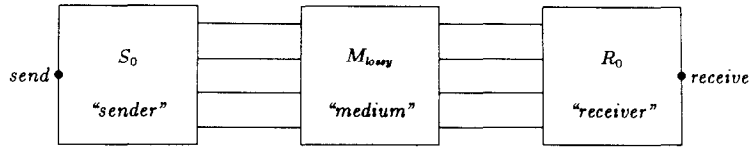
Figure 6 contains a proof of (1) using the axioms of Fig. 4 as rewrite rules. The proof of (2) follows similar lines and is left to the reader.

The second example uses priorities in a slightly different fashion. Here we present a development of the Alternating Bit Protocol [2] that is correct in pure CCS when the medium may lose messages but is incorrect when the medium is reliable. We show how the introduction of priorities resolves this anomaly. We should note that the use of priorities here is only partially successful. The inadequacy of the example is discussed more fully after its presentation, but the problem arises from the fact that only the prioritized internal move can preempt unprioritized actions.

The Alternating Bit Protocol provides a means of ensuring reliable communication over half-duplex lines. In this protocol, the sending and receiving processes alternate between two states in response to the receipt of messages (in the case of the receiving process) and acknowledgements (in the case of the sending process). Senders and receivers may also time-

$$\begin{aligned}
Sys &= [back.(X'|C) + \underline{i}.((ok.\overline{\underline{i}}.X)|C) + check.(X|\overline{\underline{i}}.\underline{i}.C)]\backslash \underline{i} \text{ by INT} \\
&= back.[(X'|C)\backslash \underline{i}] + check.[(X|\overline{\underline{i}}.\underline{i}.C)\backslash \underline{i}] \text{ by RES3, RES2 and A4} \\
&= back.[(X'|C)\backslash \underline{i}] + \\
&\quad check.[[back.(X'|\overline{\underline{i}}.\underline{i}.C) + \underline{i}.((ok.\overline{\underline{i}}.X)|\overline{\underline{i}}.\underline{i}.C) + \overline{\underline{i}}.(X|\underline{i}.C) + \underline{\tau}.((ok.\overline{\underline{i}}.X)|\underline{i}.C)]\backslash \underline{i}] \text{ by INT} \\
&= back.[(X'|C)\backslash \underline{i}] + check.[\underline{\tau}.((ok.\overline{\underline{i}}.X)|\underline{i}.C)\backslash \underline{i}] \text{ by P, RES3, RES2 and A4} \\
&= back.[(X'|C)\backslash \underline{i}] + check.\underline{\tau}.[ok.((\overline{\underline{i}}.X)|\underline{i}.C)\backslash \underline{i}] \text{ by INT, RES3, RES2 and A4} \\
&= back.[(X'|C)\backslash \underline{i}] + check.\underline{\tau}.ok.\underline{\tau}.((X|C)\backslash \underline{i}) \text{ by INT, RES3, RES2 and A4} \\
&= back.Sys' + check.\underline{\tau}.ok.\underline{\tau}.Sys \text{ by Substitution}
\end{aligned}$$

FIG. 6. A proof that $Sys =_E Spec$.



$$
\begin{aligned}
S_0 &\Leftarrow send.S_0' + \tau.S_0 \\
S_0' &\Leftarrow \overline{s_0}.(r_{ack_0}.S_1 + r_{ack_1}.S_0' + \tau.S_0') \\
S_1 &\Leftarrow send.S_1' + \tau.S_1 \\
S_1' &\Leftarrow \overline{s_1}.(r_{ack_1}.S_0 + r_{ack_0}.S_1' + \tau.S_1')
\end{aligned}
$$

$$
\begin{aligned}
M_{lossy} \Leftarrow\ & s_0.(\overline{r_0}.M_{lossy} + M_{lossy}) \\
& + s_1.(\overline{r_1}.M_{lossy} + M_{lossy}) \\
& + s_{ack_0}.(\overline{r_{ack_0}}.M_{lossy} + M_{lossy}) \\
& + s_{ack_1}.(\overline{r_{ack_1}}.M_{lossy} + M_{lossy})
\end{aligned}
$$

$$
\begin{aligned}
R_0 &\Leftarrow r_0.R_0' + r_1.\overline{s_{ack_1}}.R_0 + \tau.\overline{s_{ack_1}}.R_0 \\
R_0' &\Leftarrow receive.\overline{s_{ack_0}}.R_1 + \tau.R_0' \\
R_1 &\Leftarrow r_1.R_1' + r_0.\overline{s_{ack_0}}.R_1 + \tau.\overline{s_{ack_0}}.R_1 \\
R_1' &\Leftarrow receive.\overline{s_{ack_1}}.R_0 + \tau.R_1'
\end{aligned}
$$

$$
Sys \Leftarrow (S_0|M_{lossy}|R_0)\backslash\{r_0, r_1, s_0, s_1, r_{ack_0}, r_{ack_1}, s_{ack_0}, s_{ack_1}\}
$$

Subscripted s and r actions denote sends and receives to and from the medium, respectively. τ represents the time out action in the R_i and S_i'.

FIG. 7. The alternating bit protocol.

out while waiting for acknowledgements and messages, respectively. A full account of the protocol may be found in [2].

Figure 7 presents the development (in pure CCS) of the protocol in the context of a lossy medium. It can be proven correct—after every *send* action, the only next possible non-τ action in a *receive*, and vice versa, and the system does not deadlock (i.e., wind up in a state where no actions are possible). However, if we replace M_{lossy} with M_{safe}, a medium that does not lose messages, the protocol is no longer correct. Consider the definition of M_{safe}.

$$
M_{\text{safe}} \Leftarrow s_0.\overline{r_0}.M_{\text{safe}} + s_1.\overline{r_1}.M_{\text{safe}} + s_{\text{ack}_0}.\overline{r_{\text{ack}_0}}.M_{\text{safe}} + s_{\text{ack}_1}.\overline{r_{\text{ack}_1}}.M_{\text{safe}}.
$$

Since every s action is followed by an r action, this medium delivers every

message it receives for sending. With M_{safe} replacing M_{lossy}, however, *Sys* may deadlock; the state

$$(S_0' | \overline{r_0}.M_{\text{safe}} | \overline{s_{\text{ack}_1}}.R_0) \backslash \{r_0, r_1, s_0, s_1, r_{\text{ack}_0}, r_{\text{ack}_1}, s_{\text{ack}_0}, s_{\text{ack}_1}\}$$

is reachable via the sequence of actions

$$send\ \tau\ \tau\ \tau,$$

and no actions are possible from this state. Intuitively, this problem results from the fact that the receiver R_0 can elect to time-out (by executing its τ action) even though a message is available for it to receive from the medium.

Using prioritized actions, this situation can be prevented. By prioritizing all actions except the τ actions in S_0', S_1', R_0, and R_1 (the time-out actions), interactions with the medium that are possible are required to happen; the above state is therefore not reachable, and the protocol will behave correctly. In fact, one can prove that $Sys \simeq Spec$, where *Spec* is defined as

$$Spec \Leftarrow \underline{send}.\underline{\tau}.\underline{\tau}.Spec' + \underline{\tau}.Spec$$

$$Spec' \Leftarrow \underline{receive}.\underline{\tau}.\underline{\tau}.Spec + \underline{\tau}.Spec'.$$

Figure 8 presents a tabular representation of a relation whose symmetric closure is a bisimulation containing $\langle Sys, Spec \rangle$.

It is worth noting here that our implementation of the Alternating Bit Protocol uses busy waiting. That is, S_0, S_1, R_0', and R_1' each offer *send* and

$\{\langle Sys,$	$Spec\rangle,$
$\langle [S_0' \mid M_{safe} \mid R_0] \backslash I,$	$\underline{\tau}.\underline{\tau}.Spec'\rangle,$
$\langle [(\underline{r_{ack_0}}.S_1 + \underline{r_{ack_1}}.S_0' + \tau.S_0') \mid \overline{r_0}.M_{safe} \mid R_0] \backslash I,$	$\underline{\tau}.Spec'\rangle,$
$\langle [(\underline{r_{ack_0}}.S_1 + \underline{r_{ack_1}}.S_0' + \tau.S_0') \mid M_{safe} \mid R_0'] \backslash I,$	$Spec'\rangle,$
$\langle [(\underline{r_{ack_0}}.S_1 + \underline{r_{ack_1}}.S_0' + \tau.S_0') \mid M_{safe} \mid \overline{s_{ack_0}}.R_1] \backslash I,$	$\underline{\tau}.\underline{\tau}.Spec\rangle,$
$\langle [(\underline{r_{ack_0}}.S_1 + \underline{r_{ack_1}}.S_0' + \tau.S_0') \mid \overline{r_{ack_0}}.M_{safe} \mid R_1] \backslash I,$	$\underline{\tau}.Spec\rangle,$
$\langle [S_1 \mid M_{safe} \mid R_1] \backslash I,$	$Spec\rangle,$
$\langle [S_1' \mid M_{safe} \mid R_1] \backslash I,$	$\underline{\tau}.\underline{\tau}.Spec'\rangle,$
$\langle [(\underline{r_{ack_1}}.S_0 + \underline{r_{ack_0}}.S_1' + \tau.S_1') \mid \overline{r_1}.M_{safe} \mid R_1] \backslash I$	$\underline{\tau}.Spec'\rangle,$
$\langle [(\underline{r_{ack_1}}.S_0 + \underline{r_{ack_0}}.S_1' + \tau.S_1') \mid M_{safe} \mid R_1'] \backslash I,$	$Spec'\rangle,$
$\langle [(\underline{r_{ack_1}}.S_0 + \underline{r_{ack_0}}.S_1' + \tau.S_1') \mid M_{safe} \mid \overline{s_{ack_1}}.R_0] \backslash I,$	$\underline{\tau}.\underline{\tau}.Spec\rangle,$
$\langle [(\underline{r_{ack_1}}.S_0 + \underline{r_{ack_0}}.S_1' + \tau.S_1') \mid \overline{r_{ack_1}}.M_{safe} \mid R_1] \backslash I,$	$\underline{\tau}.Spec\rangle\ \}$

I is the set $\{\underline{r_0}, \underline{r_1}, \underline{s_0}, \underline{s_1}, \underline{r_{ack_0}}, \underline{r_{ack_1}}, \underline{s_{ack_0}}, \underline{s_{ack_1}}\}$.

FIG. 8. A relation whose symmetric closure is a bisimulation.

receive actions in the context of $\underline{\tau}$-loops. It is certainly more natural to imagine implementing the protocol without this busy waiting; however, in this case, prioritizing all actions except the τ's corresponding to time-outs does not fix the anomaly that results from the substitution of a safe medium for a lossy one. The reason is that in our semantics, only prioritized internal actions have preemptive power; prioritized external (i.e., non-$\underline{\tau}$) actions cannot override nonprioritized actions. Thus, a process can time-out when the versions of S_0, S_1, R'_0, and R'_1 without busy waiting offer a *send* or *receive*, even though these actions are prioritized.

This phenomenon merits more study; one idea for getting around it is to extend the language with a special type of prioritized actions having the preemptive power of $\underline{\tau}$. This would imply that these special actions could not be restricted or deprioritized, as otherwise $\simeq$ would cease to be a congruence. Nevertheless, such actions could play a useful role, for example, as the external actions used in specifications. In the example of the alternating bit protocol, if the *send* and *receive* actions were of this type the $\underline{\tau}$-loops representing busy waiting could be eliminated.

7. Conclusions

In this paper we have developed an operational semantics for processes having actions that take priority over other actions. Using the semantics as a basis we have developed a behavioural equivalence based on strong observational equivalence and shown that it is a congruence, and we have presented a complete axiomatization of the equivalence for finite terms and a development of proof rules for recursive processes. We have also given several examples that show the usefulness of our approach.

Much research remains to be done in order to show that our approach to priorities is indeed of general interest and applicability. In the equivalence presented in this paper, the internal actions τ and $\underline{\tau}$ play too large a role in distinguishing process; intuitively, the actions should affect our judgement of the equality of two processes only when they affect the external behavior of the processes. Accordingly, developing and axiomatizing a weak observational equivalence [11] or testing equivalence [5] based on our semantics would greatly enhance the usability of the theory. We have also indicated that a process algebra with prioritized actions should contain associated combinators such as prioritization and deprioritization and that certain other characteristics such as "strongly prioritized" actions are desirable. In general, what is a reasonable set of new combinators? Another related line of research is to examine the semantics of programming language constructs that incorporate notions of prioritization, like those mentioned in the Introduction.

An alternative approach to priorities in process algebras may be found in [1]. There the emphasis is on equational reasoning; more specifically, the authors examine the consistency of sets of equations obtained by adding to existing equational theories additional equations that the authors feel prioritization operators should satisfy. Their approach is purely algebraic in the sense that they do not give an operational semantics or behavioural equivalence that underlies their theory.

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